

# Product datasheet

Specifications



## Variable speed drive, Altivar Process ATV900, APM, single 400 V, 560 kW

ATV9A0C56Q4

### Main

Range of product	Altivar Process ATV900
Product specific application	Process and utilities
Product or component type	Variable speed drive
Device short name	ATV9A0
Variant	Modular version
Product destination	Synchronous motors Asynchronous motors
Mounting mode	Cabinet mount
Kit composition	1 control unit mechanical mounting kits power connection set of fuses 4.0 power module 160 kW 3 front cover
EMC filter	Integrated with 300 m conforming to IEC 61800-3 category C3
IP degree of protection	IP00 (for IP21 or IP54 cabinet integration) conforming to IEC 61800-5-1 IP00 (for IP21 or IP54 cabinet integration) conforming to IEC 60529
Type of cooling	Forced convection
Supply frequency	50...60 Hz +/- 5 %
Network number of phases	3 phases
[Us] rated supply voltage	400 V - 15...10 %
Prospective line Isc	50 kA
Permissible temporary current boost	1.2 x In during 60 s (normal duty) 1.5 x In during 60 s (heavy duty)
Asynchronous motor control profile	Optimized torque mode Variable torque standard Constant torque standard
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Speed drive output frequency	0.1...599 Hz
Nominal switching frequency	2.5 kHz
Switching frequency	2.5...8 kHz with derating factor 2...8 kHz adjustable
Safety function	STO (safe torque off) SIL 3
Communication port protocol	EtherNet/IP Modbus serial Modbus TCP

Excluding VAT and subject to change. Please check with your local distributor through "Where to buy"

<b>Option card</b>	Slot A: communication module for Profibus DP V1 Slot A: communication module for PROFINET Slot A: communication module for DeviceNet Slot A: communication module for EtherCAT Slot A: communication module for CANopen daisy chain RJ45 Slot A: communication module for CANopen SUB-D 9 Slot A: communication module for CANopen screw terminals Slot A/slot B/slot C: digital and analog I/O extension module Slot A/slot B/slot C: output relay extension module Slot B: 5/12 V digital encoder interface module Slot B: analog encoder interface module Slot B: resolver encoder interface module
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## Complementary

<b>Motor power kW</b>	560.0 kW at 400 V normal duty 450.0 kW at 400 V heavy duty
<b>Line current</b>	948.0 A at 400 V (normal duty) 767.0 A at 400 V (heavy duty)
<b>Apparent power</b>	657.0 kVA at 400 V normal duty 531.0 kVA at 400 V heavy duty
<b>Continuous output current</b>	1020.0 A at 2.5 kHz normal duty 830.0 A at 2.5 kHz heavy duty
<b>Maximum transient current</b>	1224.0 A during 60 s (normal duty) 1245.0 A during 60 s (heavy duty)
<b>Motor slip compensation</b>	Adjustable Automatic whatever the load Not available in permanent magnet motor law Can be suppressed
<b>Acceleration and deceleration ramps</b>	Linear adjustable separately from 0.01...9999 s
<b>Protection type</b>	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive
<b>Frequency resolution</b>	Display unit: 0.1 Hz Analog input: 0.012/50 Hz
<b>Electrical connection</b>	Control: removable screw terminals 0.5...1.5 mm <sup>2</sup> /AWG 20...AWG 16 Line side: screw terminal Motor: M10 x 2 bars
<b>Connector type</b>	2 RJ45 for Ethernet IP/Modbus TCP on the control block 1 RJ45 for Modbus serial on the control block
<b>Physical interface</b>	2-wire RS 485 for Modbus serial
<b>Transmission frame</b>	RTU for Modbus serial
<b>Transmission rate</b>	10/100 Mbit/s for Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
<b>Exchange mode</b>	Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP
<b>Data format</b>	8 bits, configurable odd, even or no parity for Modbus serial
<b>Type of polarization</b>	No impedance for Modbus serial
<b>Number of addresses</b>	1...247 for Modbus serial

<b>Method of access</b>	Slave Modbus TCP
<b>Supply</b>	External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection
<b>Local signalling</b>	Local diagnostic: 3 LED (mono/dual colour) Embedded communication status: 5 LED (dual colour) Communication module status: 2 LED (dual colour)
<b>Analogue input type</b>	AI1, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits AI2 software-configurable voltage: +/- 10 V DC, impedance: 30 kOhm, resolution 12 bits AI2 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits
<b>Discrete input type</b>	DI1...DI8 programmable, 24 V DC (<= 30 V), impedance: 3.5 kOhm DI7, DI8 programmable as pulse input: 0...30 kHz, 24 V DC (<= 30 V) STOA, STOB safe torque off, 24 V DC (<= 30 V), impedance: > 2.2 kOhm
<b>Input compatibility</b>	DI1...DI8: discrete input level 1 PLC conforming to IEC 61131-2 DI7, DI8: pulse input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to IEC 61131-2
<b>Discrete input logic</b>	Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI7, DI8), < 0.6 V (state 0), > 2.5 V (state 1) Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)
<b>Analogue output type</b>	Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 0...20 mA impedance 500 Ohm, resolution 10 bits
<b>Discrete output type</b>	Logic output DQ+ 0...1 kHz <= 30 V DC 100 mA Programmable as pulse output DQ+ 0...30 kHz <= 30 V DC 20 mA Logic output DQ- 0...1 kHz <= 30 V DC 100 mA
<b>Sampling duration</b>	2 ms +/- 0.5 ms (DI1...DI8) - discrete input 5 ms +/- 1 ms (DI7, DI8) - pulse input 1 ms +/- 1 ms (AI1, AI2, AI3) - analog input 5 ms +/- 1 ms (AQ1, AQ2) - analog output
<b>Accuracy</b>	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output
<b>Linearity error</b>	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AQ1, AQ2: +/- 0.2 % for analog output
<b>Relay output type</b>	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 1000000 cycles Configurable relay logic R3: sequence relay NO electrical durability 1000000 cycles
<b>Refresh time</b>	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
<b>Minimum switching current</b>	Relay output R1, R2, R3: 5 mA at 24 V DC
<b>Maximum switching current</b>	Relay output R1 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
<b>Insulation resistance</b>	> 1 MOhm at 500 V DC, 1 min, earth

## Environment

<b>Noise level</b>	73 dB conforming to 86/188/EEC
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<b>Maximum THDI</b>	<48 % from 80...100 % of load
<b>Electromagnetic compatibility</b>	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
<b>Pollution degree</b>	2 conforming to IEC 61800-5-1
<b>Vibration resistance</b>	1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6 0.5 gn (f= 13...200 Hz) conforming to IEC 60068-2-6
<b>Shock resistance</b>	7 gn for 11 ms conforming to IEC 60068-2-27
<b>Relative humidity</b>	5...95 % without condensation conforming to IEC 60068-2-3
<b>Ambient air temperature for operation</b>	-10...40 °C without derating 40...50 °C with derating factor
<b>Ambient air temperature for storage</b>	-40...70 °C
<b>Operating altitude</b>	0...4800 m with current derating above 1000m
<b>Environmental characteristic</b>	Chemical pollution resistance class 3C3 conforming to IEC 60721-3-3 Dust pollution resistance class 3S3 conforming to IEC 60721-3-3
<b>Standards</b>	IEC 61800-3 IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1
<b>Product certifications</b>	TÜV UL cUL
<b>Marking</b>	CE

## Contractual warranty

<b>Warranty (in months)</b>	18
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## Environmental Data

Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing “Use Better, Use Longer, Use Again” campaign to extend product lifetimes and recyclability.

[Environmental Data explained >](#)

[How we assess product sustainability >](#)

### Use Longer



#### Lifetime extension

Repair

No