

# Product datasheet

Specifications



## Variable speed drive. Altivar Machine ATV320. 2.2 kW. 380...500 V. 3 phases. compact

ATV320U22N4C

**Price: 13,221.52 ZAR**

### Main

|                              |   |
|------------------------------|---|
| Range of product             | Altivar Machine ATV320  |
| Product or component type    | Variable speed drive  |
| Product specific application | Complex machines  |
| Variant                      | Standard version<br>With disconnect switch  |
| Format of the drive          | Compact   |
| Mounting mode                | Wall mount  |
| Communication port protocol  | Modbus serial<br>CANopen  |
| Option card                  | Communication module, CANopen<br>Communication module, EtherCAT<br>Communication module, Profibus DP V1<br>Communication module, PROFINET<br>Communication module, Ethernet Powerlink<br>Communication module, EtherNet/IP<br>Communication module, DeviceNet |
| [Us] rated supply voltage    | 380...500 V - 15...10 %   |
| nominal output current       | 5.5 A   |
| Motor power kW               | 2.2 kW for heavy duty   |
| Motor power hp               | 3 hp  |
| EMC filter                   | Class C2 EMC filter integrated  |
| IP degree of protection      | IP20  |

### Complementary

|                        |   |
|------------------------|---|
| Discrete input number  | 7   |
| Discrete input type    | STO safe torque off, 24 V DC, impedance: 1.5 kOhm<br>DI1...DI6 logic inputs, 24 V DC (30 V)<br>DI5 programmable as pulse input: 0...30 kHz, 24 V DC (30 V)  |
| Discrete input logic   | Positive logic (source)<br>Negative logic (sink)  |
| Discrete output number | 3   |
| Discrete output type   | Open collector DQ+ 0...1 kHz 30 V DC 100 mA<br>Open collector DQ- 0...1 kHz 30 V DC 100 mA  |
| Analogue input number  | 3   |
| Analogue input type    | A11 voltage: 0...10 V DC, impedance: 30 kOhm, resolution 10 bits<br>A12 bipolar differential voltage: +/- 10 V DC, impedance: 30 kOhm, resolution 10 bits<br>A13 current: 0...20 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration), impedance: 250 Ohm, resolution 10 bits |
| Analogue output number | 1   |

Excluding VAT and subject to change. Please check with your local distributor through "Where to buy"

|   |   |
|---|---|
| <b>Analogue output type</b>                                 | Software-configurable current AQ1: 0...20 mA impedance 800 Ohm, resolution 10 bits<br>Software-configurable voltage AQ1: 0...10 V DC impedance 470 Ohm, resolution 10 bits  |
| <b>Relay output type</b>                                    | Configurable relay logic R1A 1 NO electrical durability 100000 cycles<br>Configurable relay logic R1B 1 NC electrical durability 100000 cycles<br>Configurable relay logic R1C<br>Configurable relay logic R2A 1 NO electrical durability 100000 cycles<br>Configurable relay logic R2C   |
| <b>Maximum switching current</b>                            | Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 250 V AC<br>Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 30 V DC<br>Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC<br>Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC<br>Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V AC<br>Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V DC |
| <b>Minimum switching current</b>                            | Relay output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC   |
| <b>Method of access</b>                                     | Slave CANopen   |
| <b>4 quadrant operation possible</b>                        | True  |
| <b>Asynchronous motor control profile</b>                   | Voltage/frequency ratio, 5 points<br>Flux vector control without sensor, standard<br>Voltage/frequency ratio - Energy Saving, quadratic U/f<br>Flux vector control without sensor - Energy Saving<br>Voltage/frequency ratio, 2 points  |
| <b>Synchronous motor control profile</b>                    | Vector control without sensor   |
| <b>Maximum output frequency</b>                             | 0.599 kHz   |
| <b>Acceleration and deceleration ramps</b>                  | Linear<br>U<br>S<br>CUS<br>Ramp switching<br>Acceleration/deceleration ramp adaptation<br>Acceleration/deceleration automatic stop with DC injection  |
| <b>Motor slip compensation</b>                              | Automatic whatever the load<br>Adjustable 0...300 %<br>Not available in voltage/frequency ratio (2 or 5 points)   |
| <b>Switching frequency</b>                                  | 2...16 kHz adjustable<br>4...16 kHz with derating factor  |
| <b>Nominal switching frequency</b>                          | 4 kHz   |
| <b>Braking to standstill</b>                                | By DC injection   |
| <b>Brake chopper integrated</b>                             | True  |
| <b>Line current</b>   | 8.7 A at 380 V (heavy duty)<br>6.6 A at 500 V (heavy duty)  |
| <b>Maximum input current</b>                                | 8.7 A   |
| <b>Maximum output voltage</b>                               | 500 V   |
| <b>Apparent power</b>                                       | 5.7 kVA at 500 V (heavy duty)   |
| <b>Network frequency</b>                                    | 50...60 Hz  |
| <b>Relative symmetric network frequency tolerance</b>       | 5 %   |
| <b>Prospective line I<sub>sc</sub></b>                      | 5 kA  |
| <b>Base load current at high overload</b>                   | 8.0 A   |
| <b>Power dissipation in W</b>                               | Fan: 74.0 W at 380 V, switching frequency 4 kHz   |
| <b>With safety function Safely Limited Speed (SLS)</b>      | True  |
| <b>With safety function Safe brake management (SBC/SBT)</b> | False   |

|  |  |
|--|--|
| With safety function Safe Operating Stop (SOS)     | False  |
| With safety function Safe Position (SP)            | False  |
| With safety function Safe programmable logic       | False  |
| With safety function Safe Speed Monitor (SSM)      | False  |
| With safety function Safe Stop 1 (SS1)             | True   |
| With sft fct Safe Stop 2 (SS2)                     | False  |
| With safety function Safe torque off (STO)         | True   |
| With safety function Safely Limited Position (SLP) | False  |
| With safety function Safe Direction (SDI)          | False  |
| Protection type                                    | Input phase breaks: drive<br>Overcurrent between output phases and earth: drive<br>Overheating protection: drive<br>Short-circuit between motor phases: drive<br>Thermal protection: drive |
| Width  | 140 mm   |
| Height   | 184.0 mm   |
| Depth  | 158.0 mm   |
| Net weight   | 2.1 kg   |
| Transient overtorque                               | 170...200 % of nominal motor torque  |

## Environment

|  |   |
|--|---|
| Operating position   | Vertical +/- 10 degree  |
| Product certifications   | CE<br>ATEX<br>NOM<br>GOST<br>EAC<br>RCM<br>KC   |
| Marking  | CE<br>ATEX<br>UL<br>CSA<br>EAC<br>RCM   |
| Standards  | IEC 61800-5-1   |
| Electromagnetic compatibility                                    | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2<br>Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3<br>Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4<br>1.2/50 $\mu$ s - 8/20 $\mu$ s surge immunity test level 3 conforming to IEC 61000-4-5<br>Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6<br>Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 |
| Environmental class (during operation)                           | Class 3C3 according to IEC 60721-3-3<br>Class 3S2 according to IEC 60721-3-3  |
| Maximum acceleration under shock impact (during operation)       | 150 m/s <sup>2</sup> at 11 ms   |
| Maximum acceleration under vibrational stress (during operation) | 10 m/s <sup>2</sup> at 13...200 Hz  |
| Maximum deflection under vibratory load (during operation)       | 1.5 mm at 2...13 Hz   |
| Permitted relative humidity (during operation)                   | Class 3K5 according to EN 60721-3   |

|                                       |   |
|---------------------------------------|---|
| Volume of cooling air                 | 37.7 m3/h   |
| Overvoltage category                  | III   |
| Regulation loop                       | Adjustable PID regulator  |
| Speed accuracy                        | +/- 10 % of nominal slip 0.2 Tn to Tn                           |
| Pollution degree                      | 2   |
| Ambient air transport temperature     | -25...70 °C   |
| Ambient air temperature for operation | -10...50 °C without derating<br>50...60 °C with derating factor |
| Ambient air temperature for storage   | -25...70 °C   |

## Packing Units

|                              |           |
|------------------------------|-----------|
| Unit Type of Package 1       | PCE       |
| Number of Units in Package 1 | 1         |
| Package 1 Height             | 24.500 cm |
| Package 1 Width              | 19.500 cm |
| Package 1 Length             | 26.700 cm |
| Package 1 Weight             | 2.652 kg  |
| Unit Type of Package 2       | P06       |
| Number of Units in Package 2 | 12        |
| Package 2 Height             | 75.000 cm |
| Package 2 Width              | 60.000 cm |
| Package 2 Length             | 80.000 cm |
| Package 2 Weight             | 45.280 kg |

## Contractual warranty

|                      |    |
|----------------------|----|
| Warranty (in months) | 18 |
|----------------------|----|



## Environmental Data

Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing “Use Better, Use Longer, Use Again” campaign to extend product lifetimes and recyclability.

[Environmental Data explained >](#)

[How we assess product sustainability >](#)

### Environmental footprint

Total lifecycle Carbon footprint 1718

Environmental Disclosure [Product Environmental Profile](#)

## Use Better

### Materials and Substances

Packaging made with recycled cardboard Yes

Packaging without single use plastic Yes

[EU RoHS Directive](#) Pro-active compliance (Product out of EU RoHS legal scope)

SCIP Number 6bbbffbe-8a69-47e2-9c29-bc773d0b789b

REACH Regulation [REACH Declaration](#)

### Energy efficiency

Product contributes to saved and avoided emissions Yes

## Use Longer

### Lifetime extension

Repair No

## Use Again

### Repack and remanufacture

End of life manual availability [End of Life Information](#)

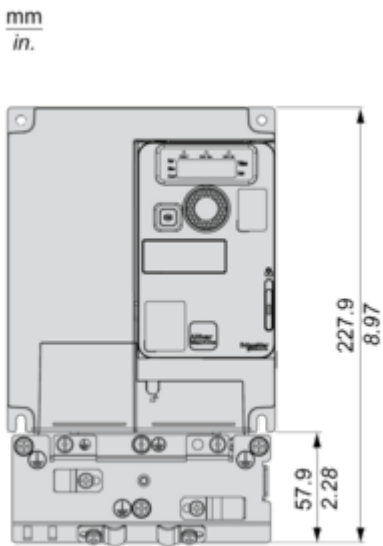
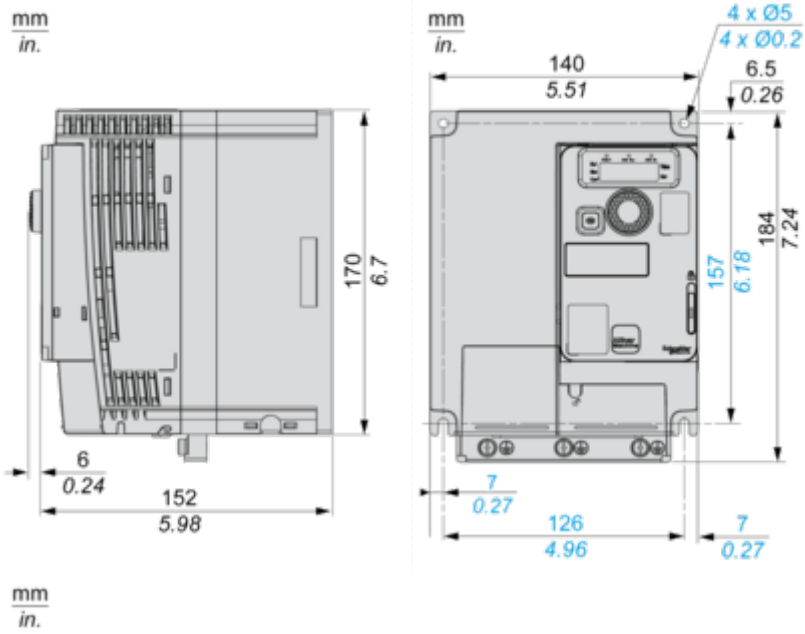
Take-back No

WEEE Label The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

Dimensions Drawings

Dimensions

Right View, Front View and Front View with EMC Plate



Mounting and Clearance

Mounting Types

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Mounting Type A: Individual with Ventilation Cover



Only Possible at Ambient Temperature Less or Equal to 50 °C (122 °F)

Mounting Type B: Side by Side, Ventilation Cover Removed



Mounting Type C: Individual, Ventilation Cover Removed



For Operation at Ambient Temperature Above 50 °C (122 °F)

Connections and Schema

Connection Diagrams

Single or Three-phase Power Supply - Diagram With Line Contactor



- (1) Line choke (if used)
- (2) Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.

Single or Three-phase Power Supply - Diagram With Downstream Contactor



- (1) Line choke (if used)
- (2) Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.

Control Block Wiring Diagram



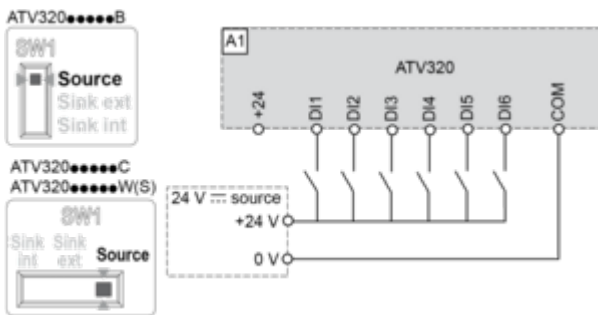
- (1) Analog output
- (2) Analog inputs
- (3) Potentiometer SZ1RV1202 (2.2 kΩ) or similar (10 kΩ maximum)
- (4) Digital Inputs - Shielding instructions are given in the Electromagnetic Compatibility section

Digital Inputs Wiring

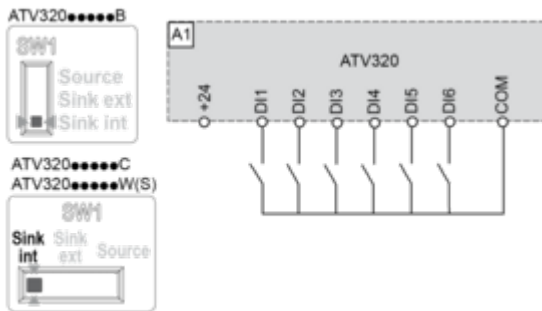
Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



Switch Set to SRC (Source) Position and Use of an External Power Supply for the Digital Inputs



Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



Switch Set to EXT Position Using an External Power Supply for the Digital Inputs



NOTE :

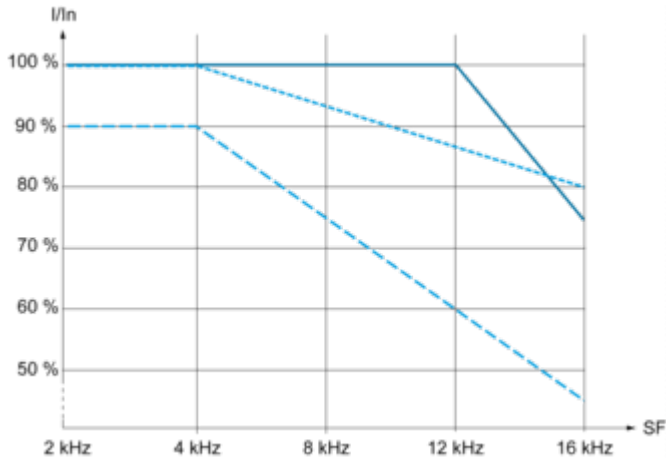
- STO input is also connected by default on a 24 Vdc terminal. If the external power supply is switched off, the function STO will be triggered.
- To avoid triggering the STO function when switching-on the product, the external power supply must be previously switched on.



Performance Curves

Derating Curves

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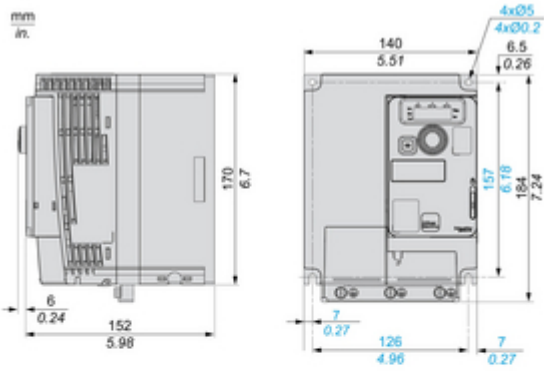


- 40 °C (104 °F) - Mounting type A, B and C
  - - - 50 °C (122 °F) - Mounting type C
  - 60 °C (140 °F) - Mounting type C
- In : Nominal Drive Current  
SF : Switching Frequency

Technical Illustration

Dimensions

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With EMC Plate

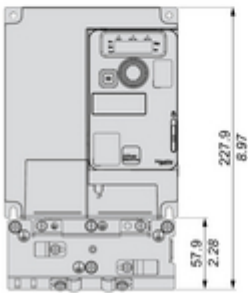


Image of product / Alternate images

Alternative

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